

HM1

General

The air pressure sensor HM1 is used to measure air pressure differences. These differences can then be used to evaluate the altitude.

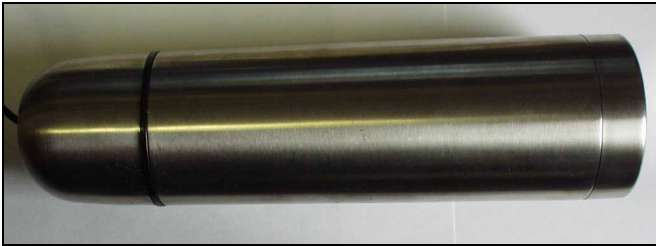


Figure 1: HM1 vacuum flask.

Output Signal

The output signal V_o is defined by

$$V_o(p) = (p_z - p) \cdot 40 \cdot k \cdot \frac{\text{V}}{\text{hPa}}$$

where k is the switch position ($k = 1$ or 2), p is the air pressure, and p_z is the reference pressure, which can be adjusted with a 10-turns-potentiometer. The reference pressure range begins at 1035 hPa and ends at 1085 hPa (5 hPa per potentiometer revolution ≈ 40 metres per revolution).

Pin Assignment

Output plug: The output plug is manufactured by Binder (Binder Series 719). It supplies the HM1 with voltage and puts out the pressure dependent voltages.

Pin	Assignment [Cable colour]
1	Supplying voltage (7 V to 16 V DC) [red]
2	Ground [brown]
3	Signal Output (0 V to 4.9 V) [black]
4	
5	(unused)

Specifications

Supply Voltage Range: 7 V to 16 V DC

Power Consumption (typical): 10 mA

Output Voltage Range: 0 V to 4.9 V

Mechanical Data

Vacuum flask (stainless steel):

Ø 80 mm; Height: 300 mm;

Weight: 650 g

Altitude

The international altitude formula is given by

$$p(h) = 1.013 \cdot 10^5 \text{ Pa} \left(1 - \frac{6.5}{288000 \text{ m}} h \right)^{5.255}$$

where p is the air pressure and h is the altitude. Resolving this equation yields

$$h(p) = \frac{288000}{6.5} \text{ m} \left(1 - \left(\frac{p}{1.013 \cdot 10^5 \text{ Pa}} \right)^{\frac{1}{5.255}} \right)$$

Altitude Approximation

Due to limited mathematical capabilities of data loggers and signal converters, the altitude formula can be approximated by using simple integer arithmetic: First, the air pressure p is substituted with its corresponding bit value b , and second, only the first few terms of the Taylor series at air pressure p_0 are taken into account. Thus,

$$h(b) \approx -200 \text{ m} + \frac{1}{10} \text{ m} \left(a_0 + \sum_{i=1}^3 \frac{(a_i \cdot b)^i}{65535^{i-1}} \right)$$

TEMES Calculation Instructions

No	Operation
F1	$h_1 = \text{Op}_4(Q_1 = p, K_1 = a_3, K_2 = 0)$
F2	$h_2 = \text{Op}_7(Q_1 = Q_2 = h_1, K_1 = 65535)$
F3	$h_3 = \text{Op}_7(Q_1 = h_1, Q_2 = h_2, K_1 = 65535)$
F4	$h_4 = \text{Op}_4(Q_1 = p, K_1 = a_2, K_2 = 0)$
F5	$h_5 = \text{Op}_7(Q_1 = Q_2 = h_4, K_1 = 65535)$
F6	$h_6 = \text{Op}_4(Q_1 = p, K_1 = a_1, K_2 = 0)$
F7	$h_7 = \text{Op}_5(Q_1 = h_6, Q_2 = h_5, K_1 = 1)$
F8	$h_8 = \text{Op}_5(Q_1 = h_7, Q_2 = h_3, K_1 = 1)$
F9	$h = \text{Op}_4(Q_1 = h_8, K_1 = 1, K_2 = a_0)$
<u>Assignment:</u> $b(h = -200 \text{ m}) = 0 \text{ bit}$ $b(h = -199 \text{ m}) = 10 \text{ bit}$	

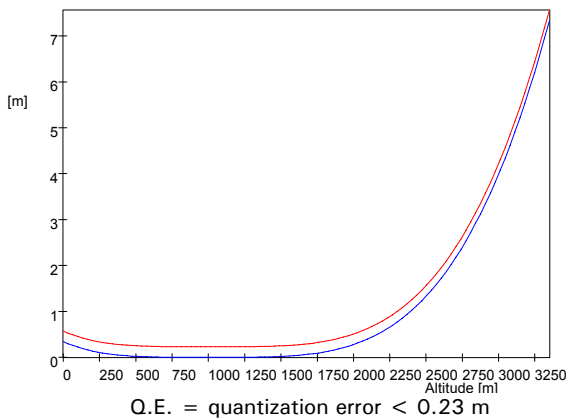
Approximation for $h \leq 3350 \text{ m}$

Given Switch position $k = 2$
 $h(p_0) = 1000 \text{ m}$
Working Range: $V(p = 1060 \text{ hPa}) = 0 \text{ V}$
 $V(p = 660 \text{ hPa}) = 5 \text{ V}$

Assumption: $V(0 \text{ bit}) = 0 \text{ V}$
 $V(63937.5 \text{ bit}) = 5 \text{ V}$

Result $a_3 = 0.3078701171$
 $a_2 = 0.2674385051$
 $a_1 = 0.5038948203$
 $a_0 = -1853.468621$
 $h \in [-200\text{m}; 3350\text{m}]$

Max. Abs. Approximation Error (with and without Q.E.)

**Approximation for $h \leq 1350 \text{ m}$**

Given Switch position $k = 1$
 $h(p_0) = 260 \text{ m}$
Working Range: $U(p = 1060 \text{ hPa}) = 0 \text{ V}$
 $U(p = 860 \text{ hPa}) = 5 \text{ V}$

Assumption: $U(0 \text{ bit}) = 0 \text{ V}$
 $U(63937.5 \text{ bit}) = 5 \text{ V}$

Result $a_3 = 0.1416195918$
 $a_2 = 0.1390062029$
 $a_1 = 0.251055528$
 $a_0 = -1841.009177$
 $h \in [-200\text{m}; 1350\text{m}]$

Max. Abs. Approximation Error (with and without Q.E.)

